

# Classification of Quadratic Forms

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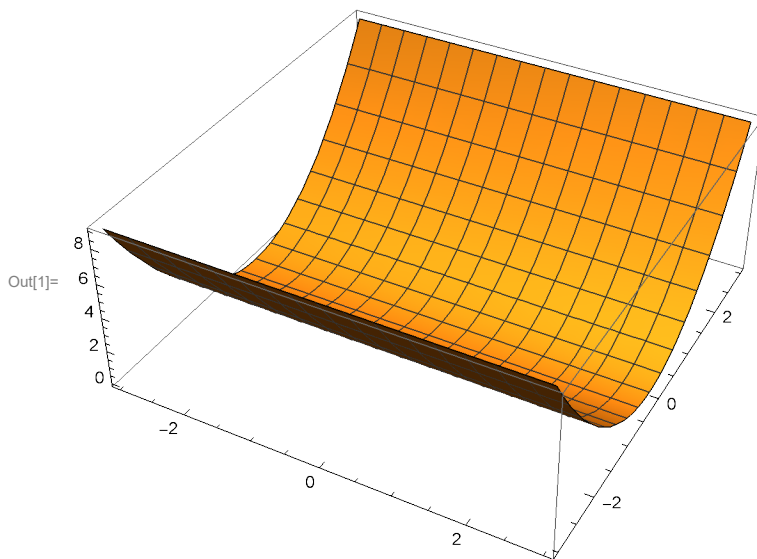
## Quadratic Forms on $\mathbb{R}^2$

Eigenvalues: 0 (zero quadratic form)

Eigenvalues: 0, 1 (positive semi-definite quadratic form)

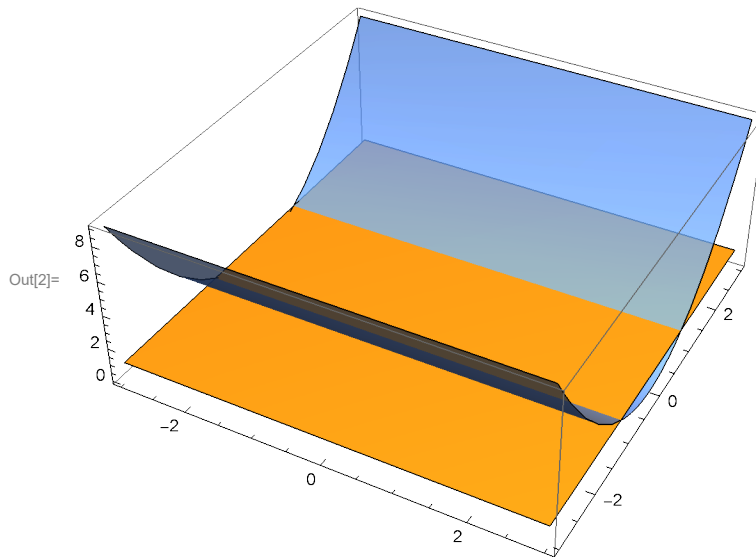
In this case  $Q(\mathbf{x}) = (x_2)^2$

In[1]= `Plot3D[y^2, {x, -3, 3}, {y, -3, 3}]`

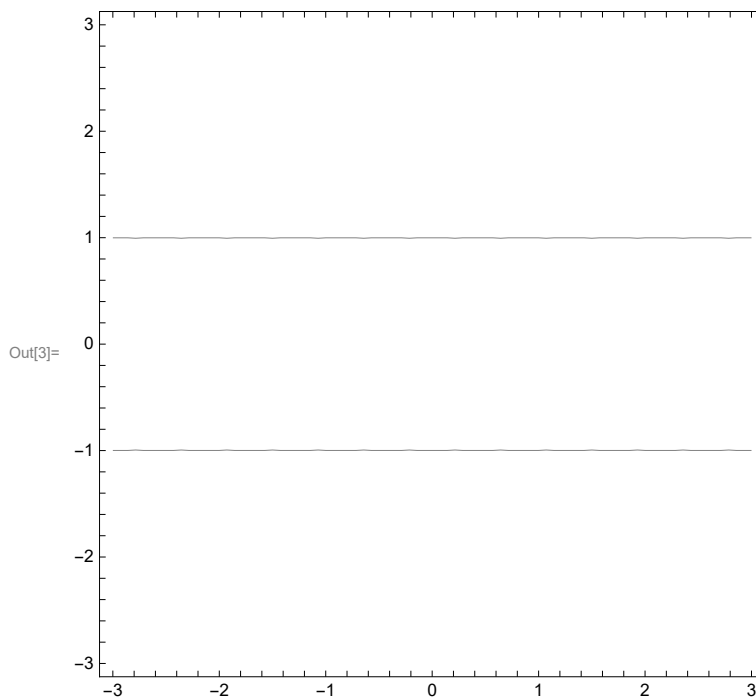


(I) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = 1\}$  is the union of two parallel lines  $x_2 = 1$  and  $x_2 = -1$ .

```
In[2]:= Plot3D[{1, y^2}, {x, -3, 3}, {y, -3, 3}, Mesh -> False, PlotStyle -> {{}, {Opacity[0.75]}}
```

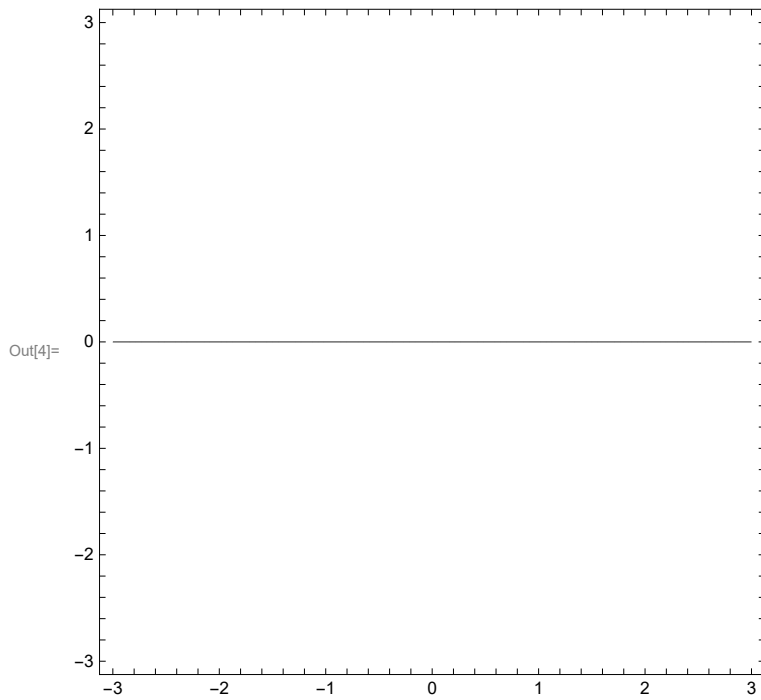


```
In[3]:= ContourPlot[y^2, {x, -3, 3}, {y, -3, 3}, Contours -> {1}, ContourShading -> False]
```



(II) The set  $\{x \in \mathbb{R}^2 : Q(x) = 0\}$  is the  $x_1$ -axis

```
In[4]:= ContourPlot[y2, {x, -3, 3}, {y, -3, 3}, Contours → {0.00001}, ContourShading → False]
```

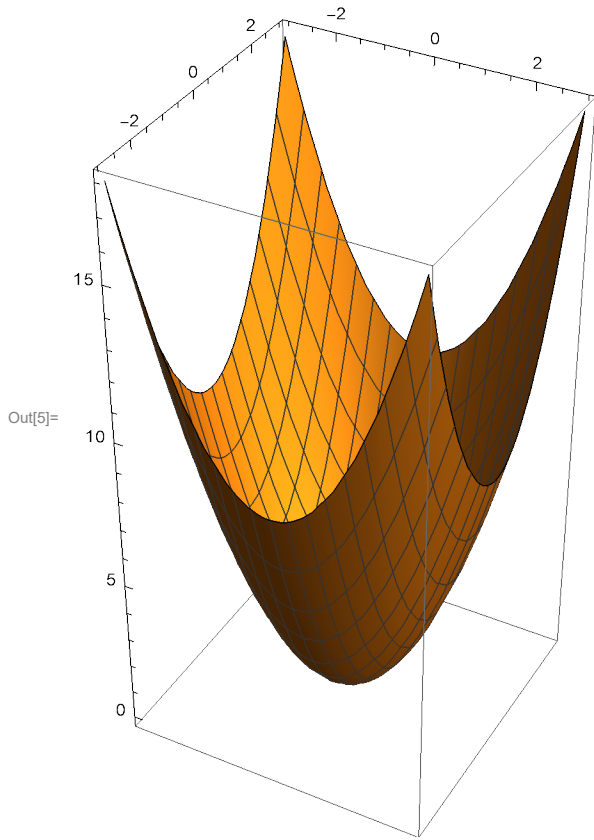


(III) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = -1\}$  is empty.

**Eigenvalues: 1, 1 (positive definite quadratic form)**

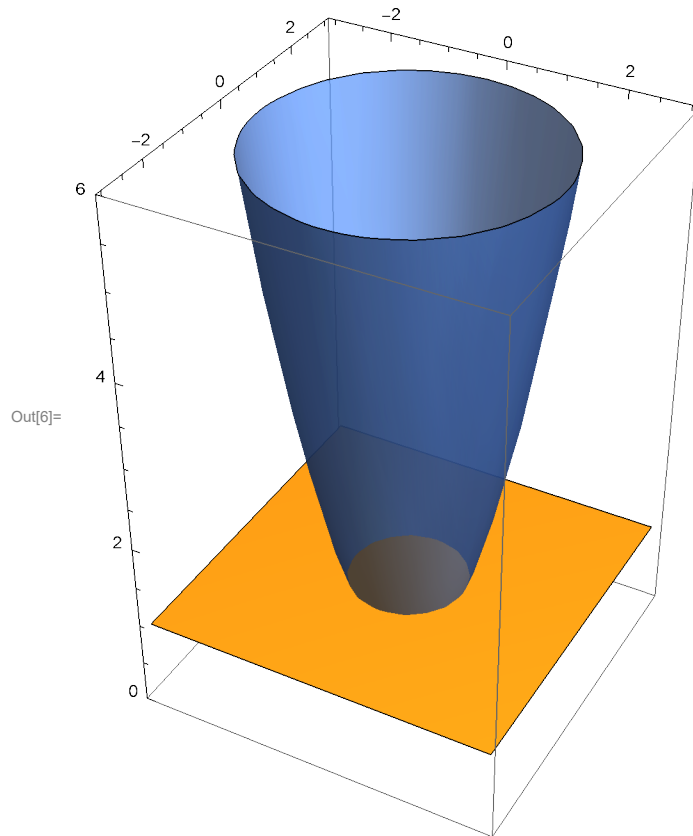
In this case  $Q(\mathbf{x}) = (x_1)^2 + (x_2)^2$

```
In[5]:= Plot3D[x2 + y2, {x, -3, 3}, {y, -3, 3}, BoxRatios -> {1, 1, 2}]
```

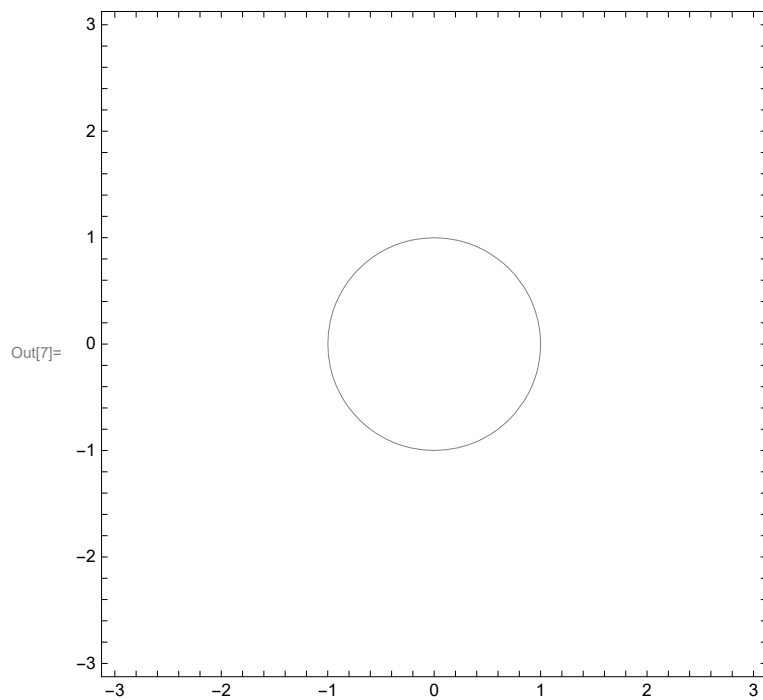


(I) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = 1\}$  is the unit circle in  $\mathbb{R}^2$ :  $(x_1)^2 + (x_2)^2 = 1$ .

```
In[6]:= Plot3D[{1, x^2 + y^2}, {x, -3, 3}, {y, -3, 3}, Mesh -> False, PlotStyle -> {{}, {Opacity[0.75]}},  
PlotRange -> {0, 6}, BoxRatios -> {1, 1, 3/2}, ClippingStyle -> None]
```

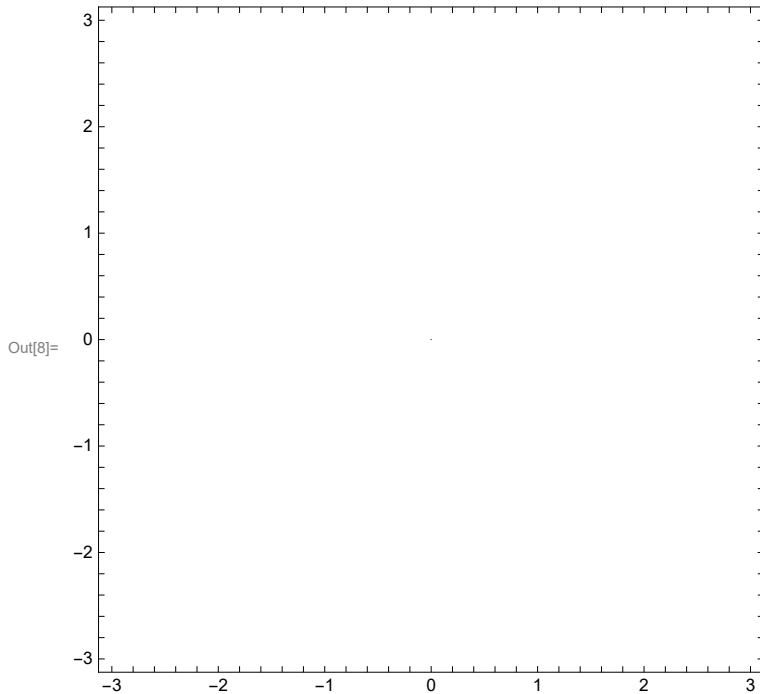


```
In[7]:= ContourPlot[x^2 + y^2, {x, -3, 3}, {y, -3, 3}, Contours -> {1}, ContourShading -> False]
```



(II) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = 0\}$  is the set which consists of only one point, the origin  $(0, 0)$ .

In[8]:= `ContourPlot[x2 + y2, {x, -3, 3}, {y, -3, 3}, Contours -> {0.0001}, ContourShading -> False]`



(III) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = -1\}$  is the empty set.

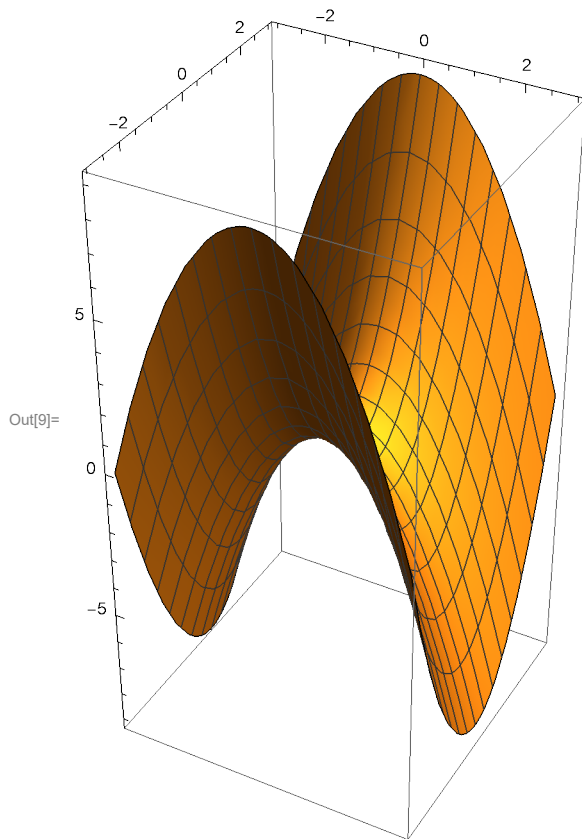
Eigenvalues: 0, -1 (negative semi-definite quadratic form)

Eigenvalues: -1, -1 (negative definite quadratic form)

Eigenvalues: -1, 1 (indefinite quadratic form)

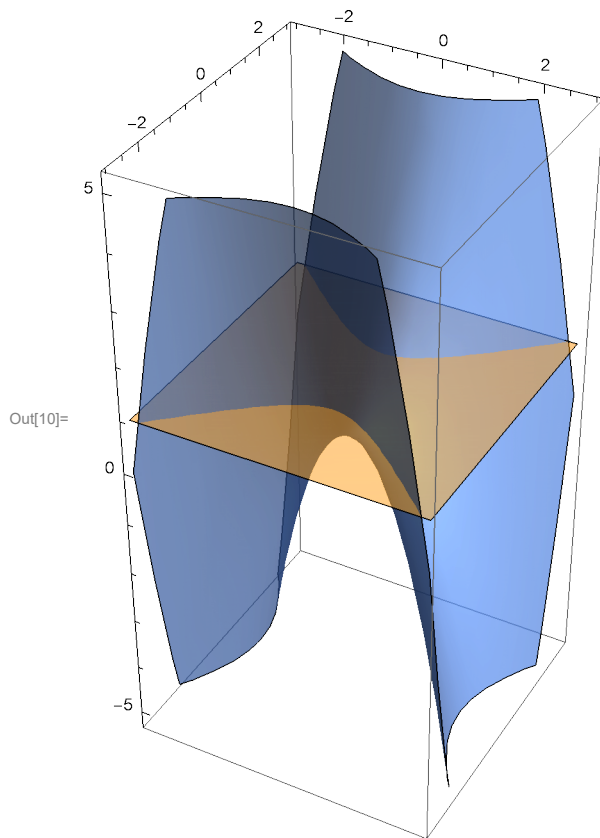
In this case  $Q(\mathbf{x}) = -(x_1)^2 + (x_2)^2$

```
In[9]:= Plot3D[-x^2 + y^2, {x, -3, 3}, {y, -3, 3}, BoxRatios -> {1, 1, 2}]
```

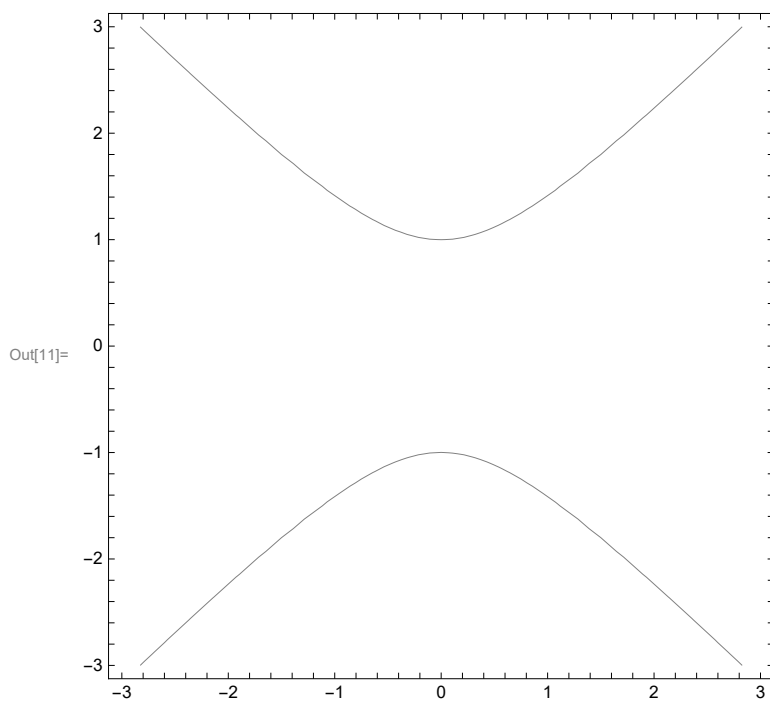


(I) The set  $\{\mathbf{x} \in \mathbb{R}^2 : Q(\mathbf{x}) = 1\}$  is the hyperbola in  $\mathbb{R}^2$ :  $-(x_1)^2 + (x_2)^2 = 1$ .

```
In[10]:= Plot3D[{1, -x2 + y2}, {x, -3, 3}, {y, -3, 3}, Mesh → False,  
PlotStyle → {{Opacity[0.5]}, {Opacity[0.7]}}, BoxRatios → {1, 1, 2}, ClippingStyle → None]
```



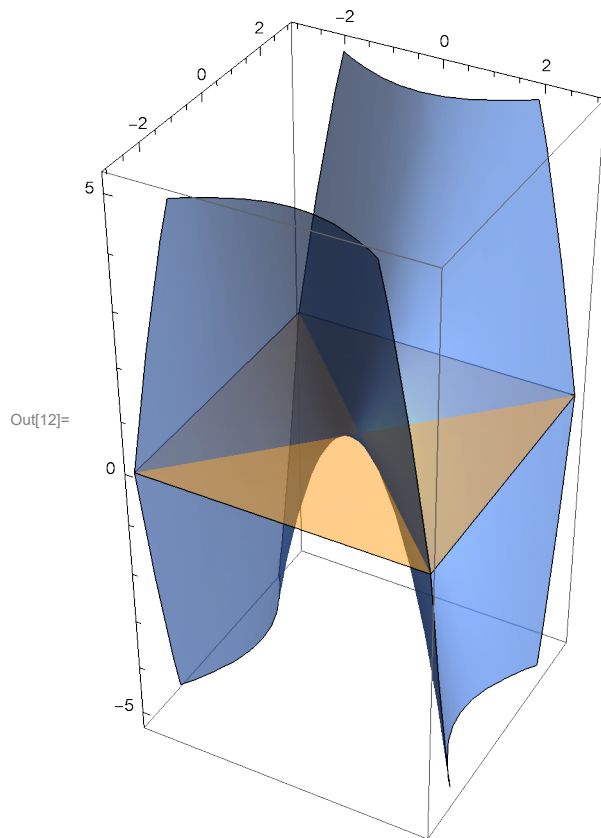
```
In[11]:= ContourPlot[-x2 + y2, {x, -3, 3}, {y, -3, 3}, Contours → {1}, ContourShading → False]
```



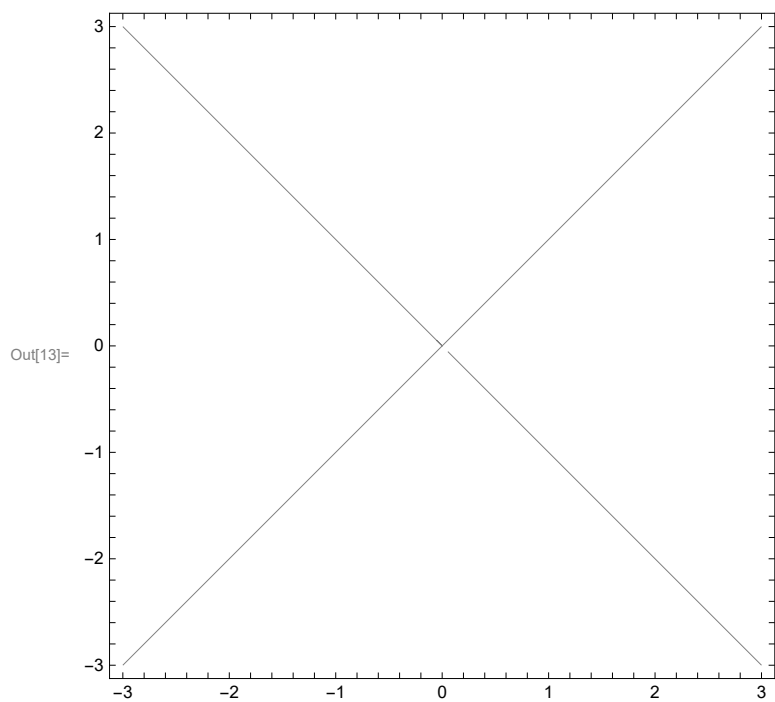


(II) The set  $\{x \in \mathbb{R}^2 : Q(x) = 0\}$  is the set which consists of two lines,  $x_1 = x_2$  and  $x_1 = -x_2$ .

```
In[12]:= Plot3D[{0, -x^2 + y^2}, {x, -3, 3}, {y, -3, 3}, Mesh -> False,  
PlotStyle -> {{Opacity[0.5]}, {Opacity[0.7]}}, BoxRatios -> {1, 1, 2}, ClippingStyle -> None]
```

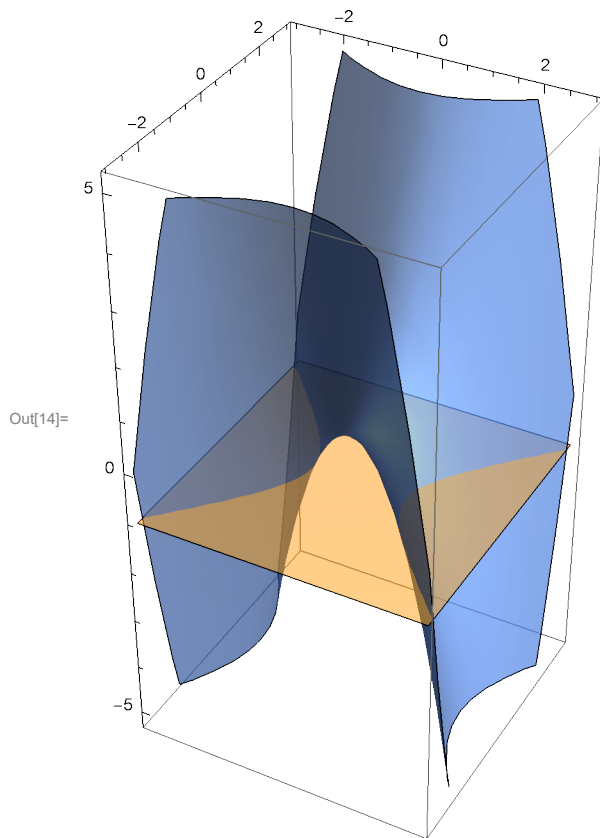


```
In[13]:= ContourPlot[-x^2 + y^2, {x, -3, 3}, {y, -3, 3}, Contours -> {0}, ContourShading -> False]
```

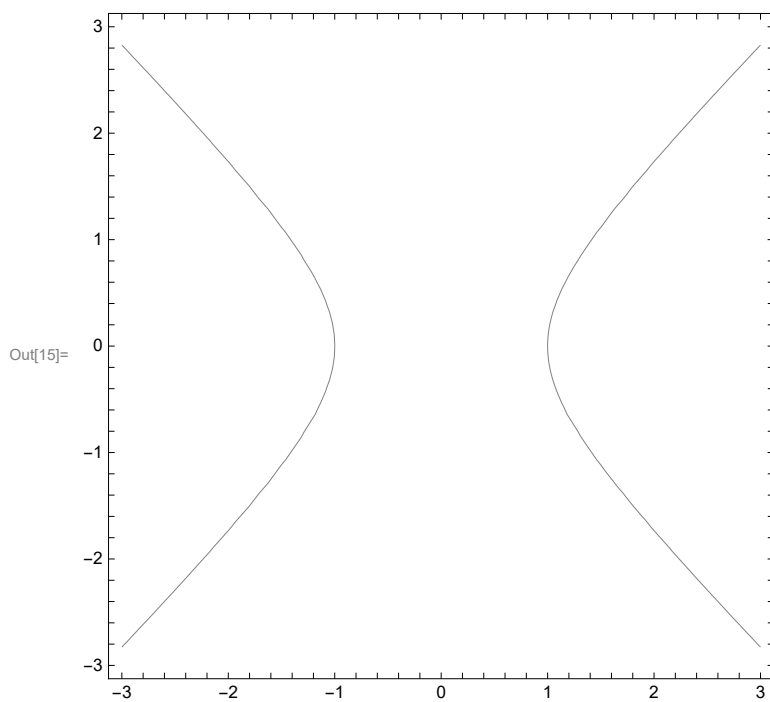


(III) The set  $\{x \in \mathbb{R}^2 : Q(x) = -1\}$  is the hyperbola in  $\mathbb{R}^2$ :  $(x_1)^2 - (x_2)^2 = 1$ .

```
In[14]= Plot3D[{-1, -x2 + y2}, {x, -3, 3}, {y, -3, 3}, Mesh → False,  
PlotStyle → {{Opacity[0.5]}, {Opacity[0.7]}}, BoxRatios → {1, 1, 2}, ClippingStyle → None]
```



```
In[15]= ContourPlot[-x2 + y2, {x, -3, 3}, {y, -3, 3}, Contours → {-1}, ContourShading → False]
```



## Quadratic Forms on $\mathbb{R}^3$

### Eigenvalues: 0 (zero quadratic form)

In this case  $Q(\mathbf{x}) = 0$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is empty.

(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is  $\mathbb{R}^3$ .

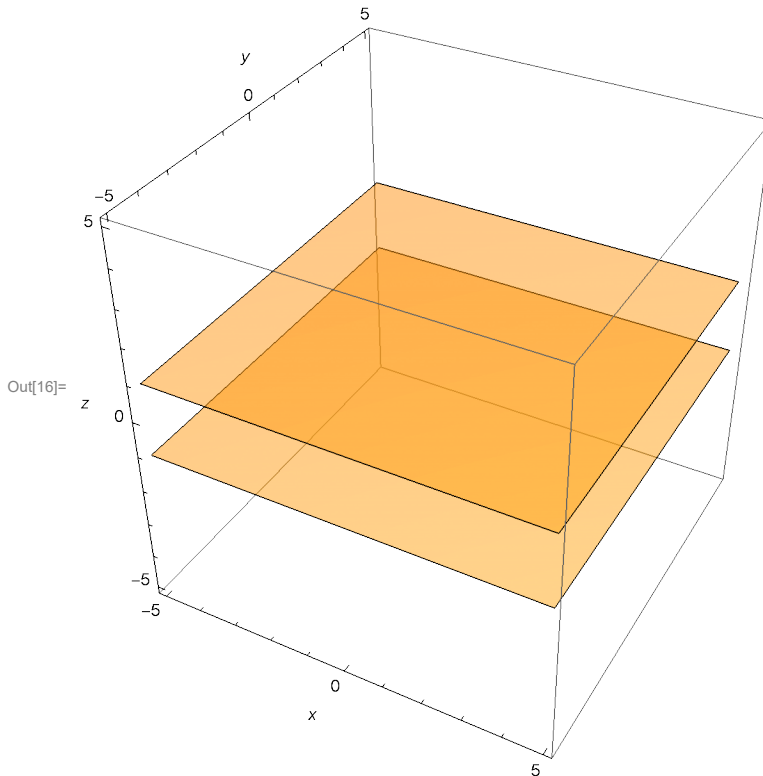
(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is empty.

### Eigenvalues: 0, 0, 1 (positive semi-definite quadratic form)

In this case  $Q(\mathbf{x}) = (x_3)^2$

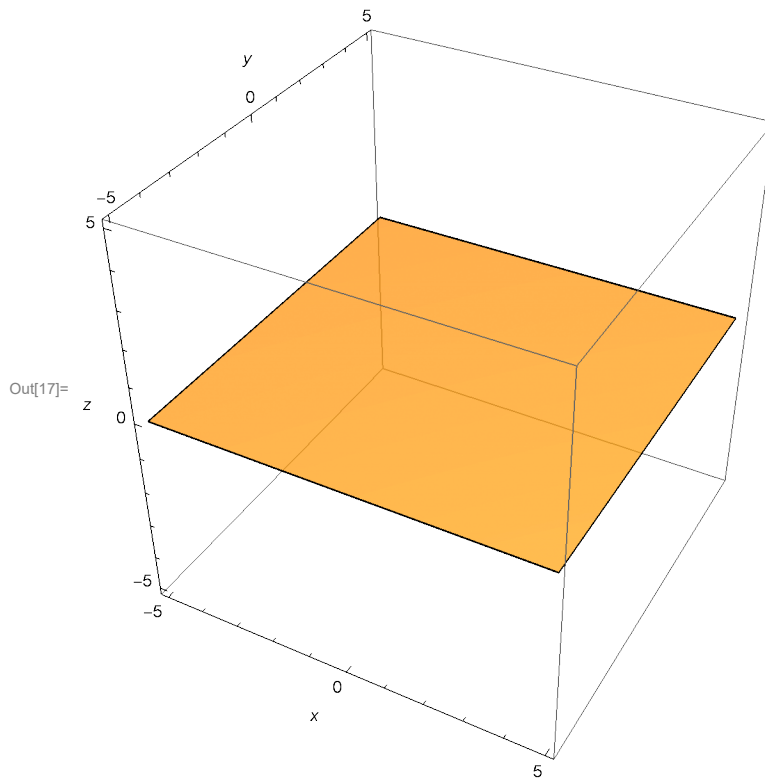
(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the union of two parallel planes  $x_3 = 1$  and  $x_3 = -1$  ( $x_1, x_2$  are arbitrary).

In[16]:= `ContourPlot3D[z2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5}, Contours -> {1}, Mesh -> False, ContourStyle -> {Opacity[0.5]}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]`



(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the  $x_1 x_2$ -plane.

```
In[17]:= ContourPlot3D[z^2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5}, Contours -> {0.0001}, Mesh -> False,
ContourStyle -> {Opacity[0.5]}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```



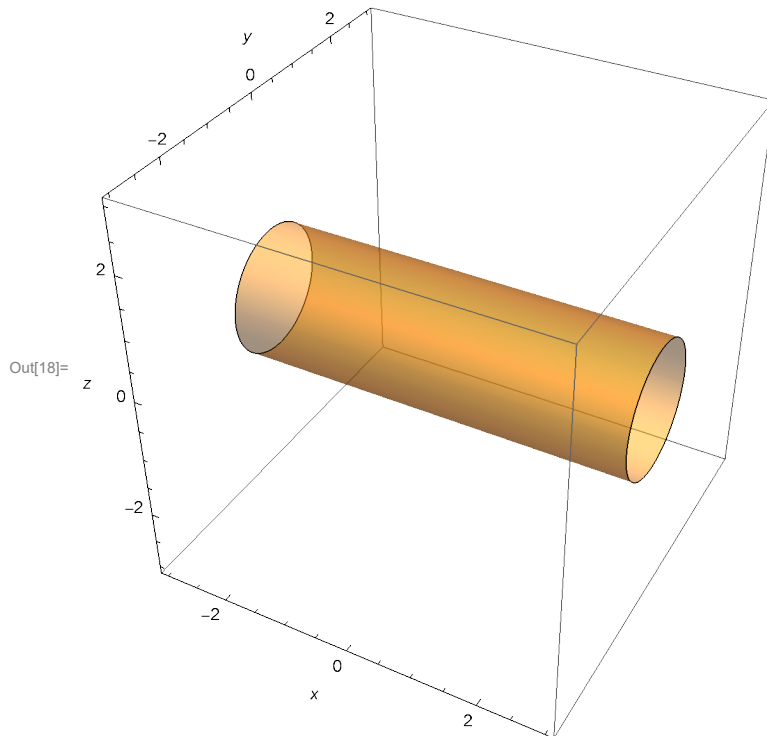
(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the empty set.

### Eigenvalues: 0, 1, 1 (positive semi-definite quadratic form)

In this case  $Q(\mathbf{x}) = (x_2)^2 + (x_3)^2$

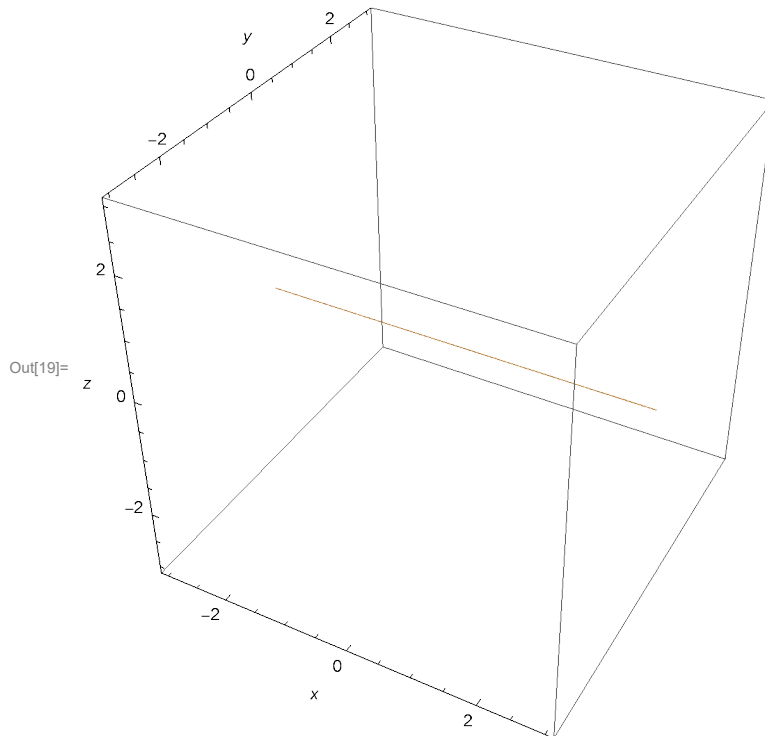
(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the circular cylinder parallel to  $x_1$ -axis whose directrix is the unit circle in  $x_2 x_3$ -plane.

```
In[18]:= ContourPlot3D[y2 + z2, {x, -3, 3}, {y, -3, 3}, {z, -3, 3}, Contours → {1}, Mesh → False,  
ContourStyle → {Opacity[0.5]}, PlotPoints → {100, 100, 100}, AxesLabel → {x, y, z}]
```



(II) The set  $\{x \in \mathbb{R}^3 : Q(x) = 0\}$  is the  $x_1$ -axis.

```
In[19]:= ContourPlot3D[y2 + z2, {x, -3, 3}, {y, -3, 3}, {z, -3, 3}, Contours → {0.0001}, Mesh → False,
ContourStyle → {Opacity[0.5]}, PlotPoints → {100, 100, 100}, AxesLabel → {x, y, z}]
```



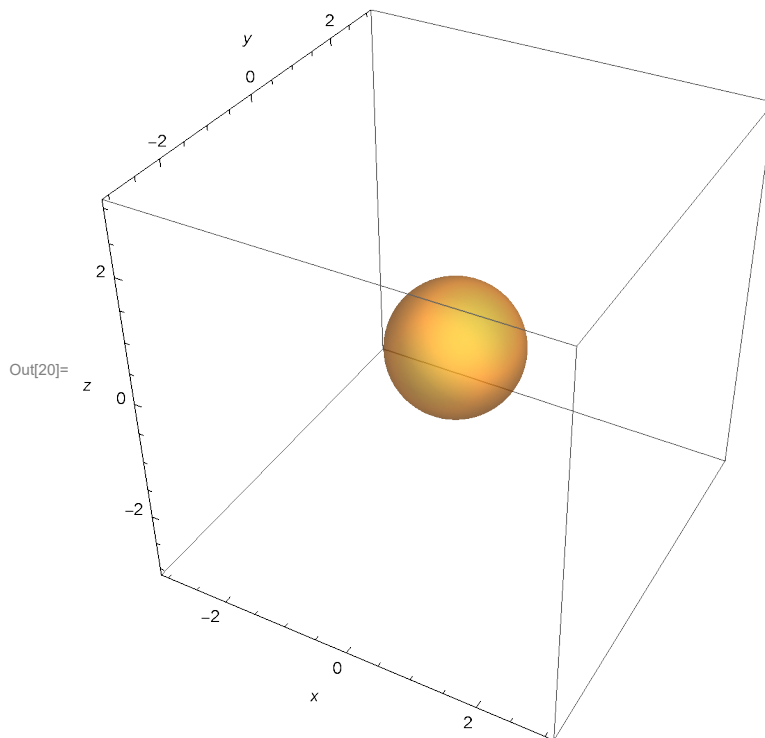
(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the empty set.

### Eigenvalues: 1, 1, 1 (positive definite quadratic form)

In this case  $Q(\mathbf{x}) = (x_1)^2 + (x_2)^2 + (x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the unit sphere.

```
In[20]= ContourPlot3D[x^2 + y^2 + z^2, {x, -3, 3}, {y, -3, 3}, {z, -3, 3}, Contours -> {1}, Mesh -> False,
ContourStyle -> {Opacity[0.5]}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```



(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the set which consists of only one point, the origin  $(0, 0, 0)$ .

(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the empty set.

### Eigenvalues: 0, 0, -1 (negative semi-definite quadratic form)

In this case  $Q(\mathbf{x}) = -(x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the empty set.

(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the  $x_1 x_2$ -plane.

(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the union of two parallel planes  $x_3 = 1$  and  $x_3 = -1$  ( $x_1, x_2$  are arbitrary).

### Eigenvalues: 0, -1, -1 (negative semi-definite quadratic form)

In this case  $Q(\mathbf{x}) = -(x_2)^2 - (x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the empty set.

(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the  $x_1$ -axis.

(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the circular cylinder parallel to  $x_1$ -axis whose directrix is the unit circle in  $x_2 x_3$ -plane.



## Eigenvalues: -1, -1, -1 (negative definite quadratic form)

In this case  $Q(\mathbf{x}) = -(x_1)^2 - (x_2)^2 - (x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the empty set.

(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the empty set.

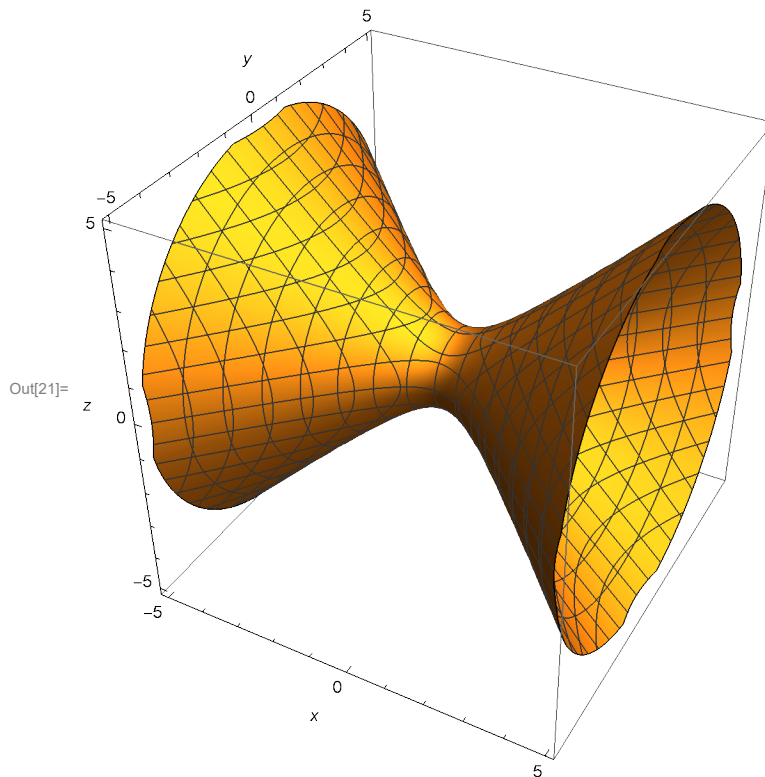
(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the unit sphere.

## Eigenvalues: -1, 1, 1 (indefinite quadratic form)

In this case  $Q(\mathbf{x}) = -(x_1)^2 + (x_2)^2 + (x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the one-sheet hyperboloid. This surface can be visualized as one branch of the hyperbola  $-(x_1)^2 + (x_3)^2 = 1$  rotating about  $x_1$ -axis.

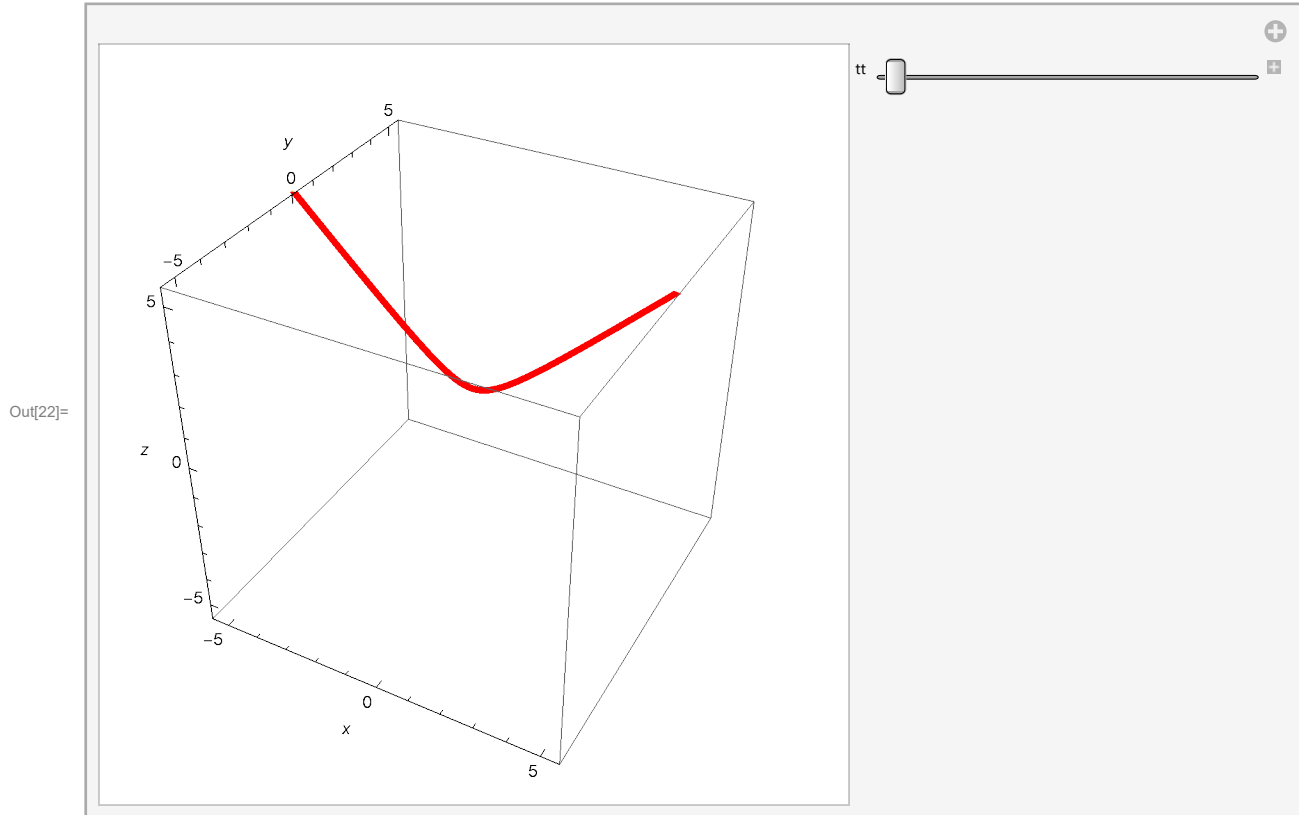
```
In[21]:= ContourPlot3D[-x^2 + y^2 + z^2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5},
  Contours -> {1}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```



```

In[22]= Manipulate[Show[ParametricPlot3D[{Sinh[s], Cosh[s] Sin[θ], Cosh[s] Cos[θ]},
  {s, -5, 5}, {θ, 0, tt}], PlotPoints → {50, 64}, Mesh → False],
  ParametricPlot3D[{Sinh[s], Cosh[s] Sin[tt], Cosh[s] Cos[tt]}, {s, -5, 5},
  PlotPoints → {50}], PlotStyle → {{Thickness[0.01], RGBColor[1, 0, 0]}},
  PlotRange → {{-5, 5}, {-5, 5}, {-5, 5}}, AxesLabel → {x, y, z}], {tt, 0.01, 2 Pi}]

```



(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the circular cone whose axes is the  $x_1$ -axes.

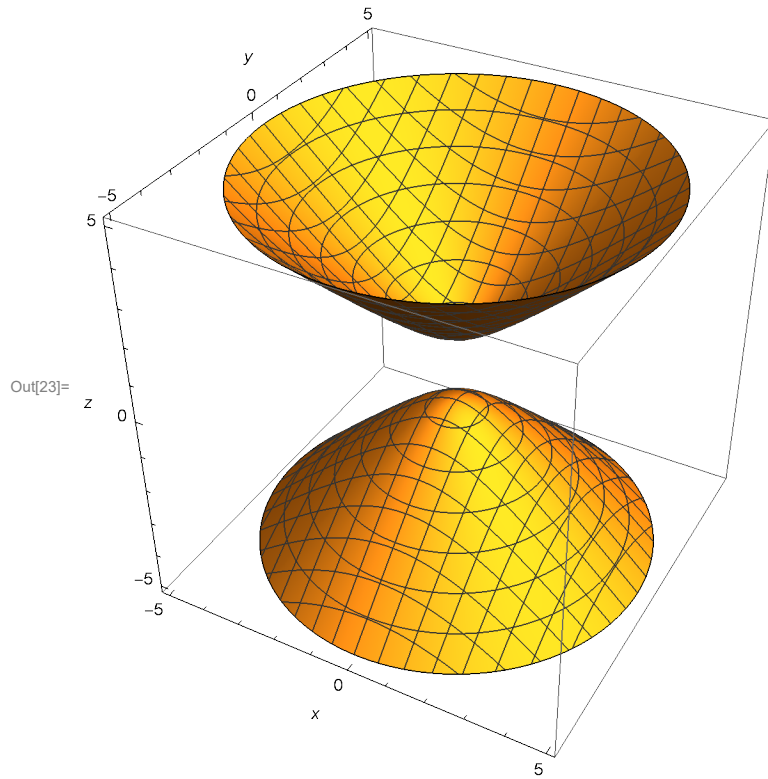
(III) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the two-sheet hyperboloid.

### Eigenvalues: -1, -1, 1 (indefinite quadratic form)

In this case  $Q(\mathbf{x}) = -(x_1)^2 - (x_2)^2 + (x_3)^2$

(I) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 1\}$  is the two-sheet hyperboloid. This surface can be visualized as the hyperbola  $-(x_1)^2 + (x_3)^2 = 1$  rotating about  $x_3$ -axis.

```
In[23]:= ContourPlot3D[-x2 - y2 + z2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5},  
Contours -> {1}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```

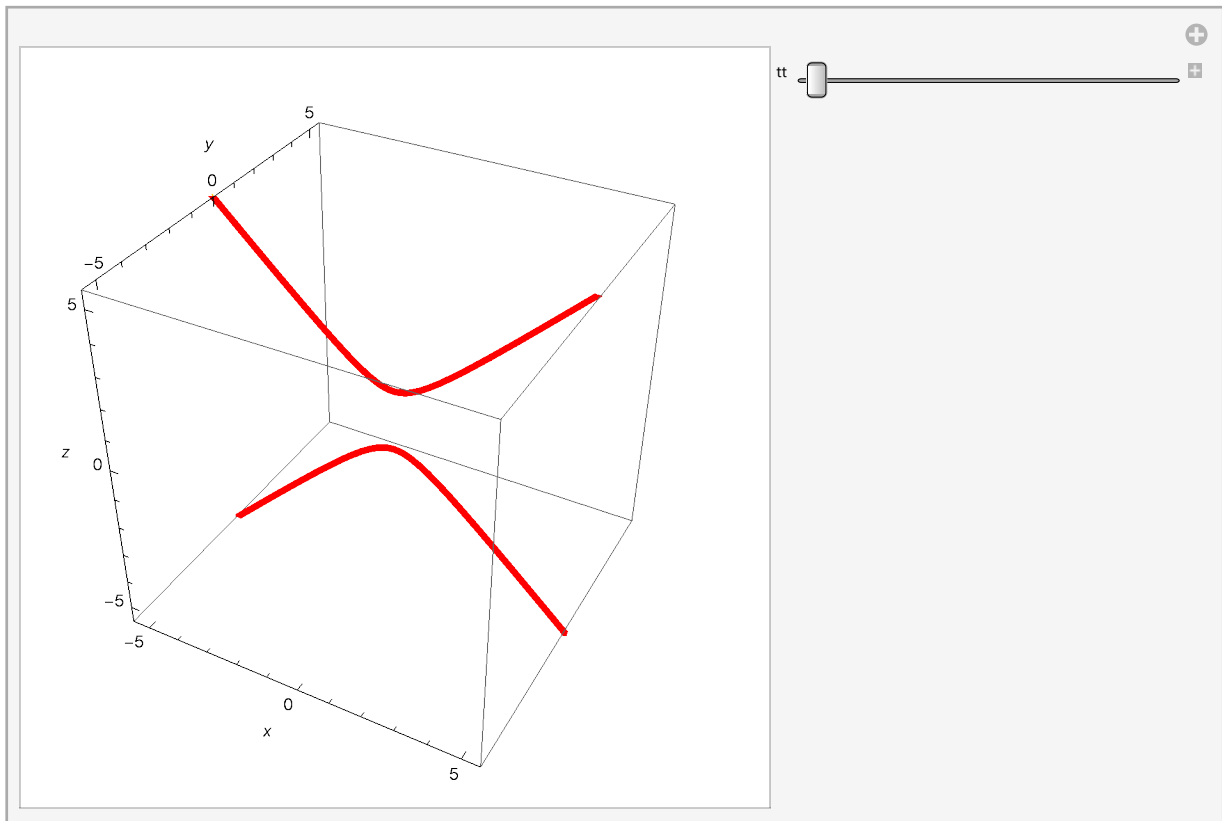


```

In[24]:= Manipulate[Show[ParametricPlot3D[{Sinh[s] Cos[θ], Sinh[s] Sin[θ], Cosh[s]},
  {s, -5, 5}, {θ, 0, tt}, PlotPoints → {50, 64}, Mesh → False],
  ParametricPlot3D[{Sinh[s] Cos[θ], Sinh[s] Sin[θ], -Cosh[s]},
  {s, -5, 5}, {θ, 0, tt}, PlotPoints → {50, 64}, Mesh → False],
  ParametricPlot3D[{Sinh[s] Cos[tt], Sinh[s] Sin[tt], Cosh[s]}, {s, -5, 5},
  PlotPoints → {50}], PlotStyle → {{Thickness[0.01], RGBColor[1, 0, 0]}}],
  ParametricPlot3D[{Sinh[s] Cos[tt], Sinh[s] Sin[tt], -Cosh[s]}, {s, -5, 5},
  PlotPoints → {50}], PlotStyle → {{Thickness[0.01], RGBColor[1, 0, 0]}}],
  PlotRange → {{-5, 5}, {-5, 5}, {-5, 5}}, AxesLabel → {x, y, z}], {tt, 0.01, Pi}]

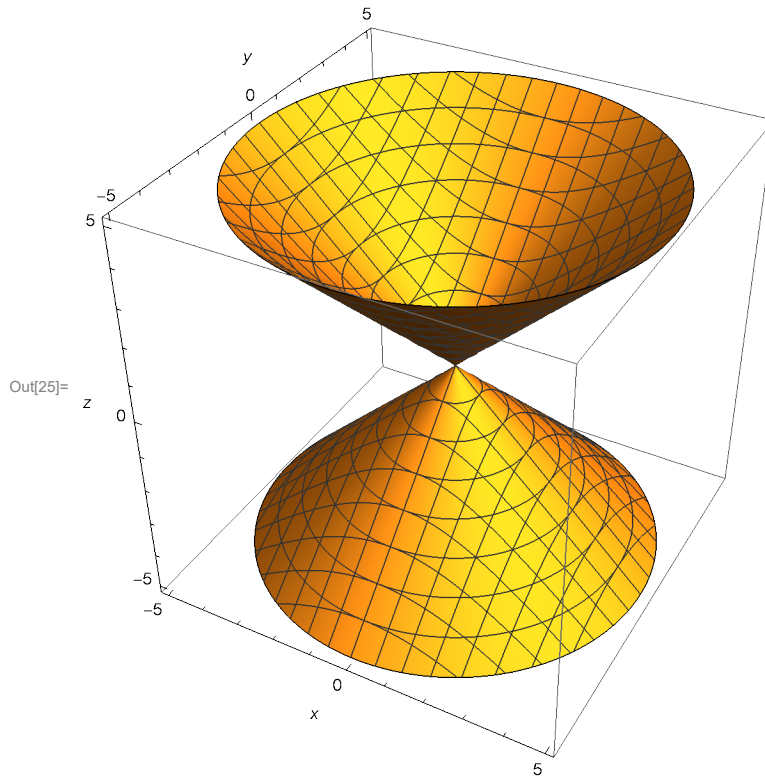
```

Out[24]=



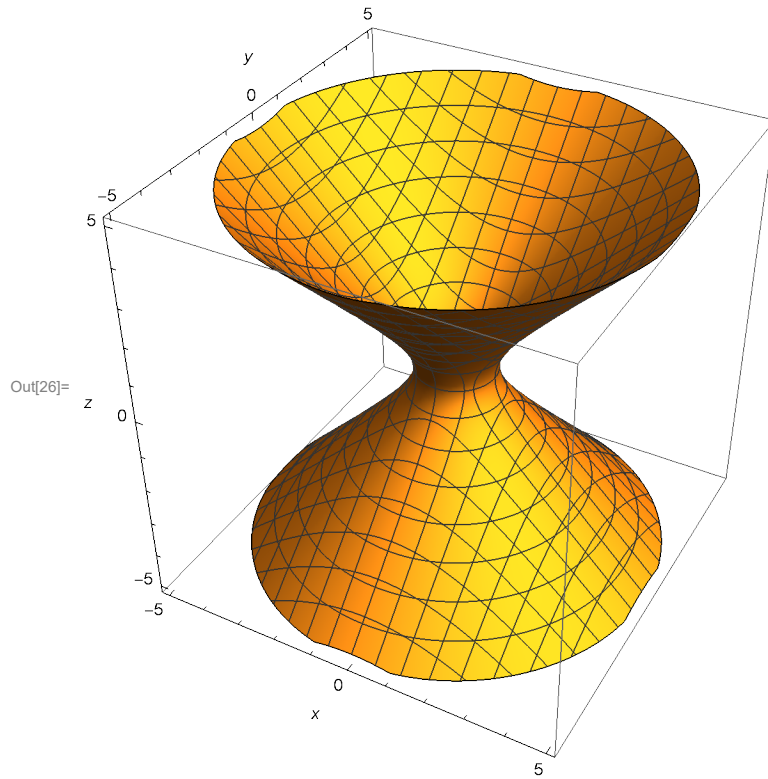
(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = 0\}$  is the circular cone whose axes is the  $x_3$ -axes.

```
In[25]:= ContourPlot3D[-x2 - y2 + z2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5},
  Contours -> {0}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```



(II) The set  $\{\mathbf{x} \in \mathbb{R}^3 : Q(\mathbf{x}) = -1\}$  is the one-sheet hyperboloid. This surface can be visualized as one branch of the hyperbola  $(x_1)^2 - (x_3)^2 = 1$  rotating about  $x_3$ -axis.

```
In[26]:= ContourPlot3D[-x2 - y2 + z2, {x, -5, 5}, {y, -5, 5}, {z, -5, 5},  
Contours -> {-1}, PlotPoints -> {100, 100, 100}, AxesLabel -> {x, y, z}]
```

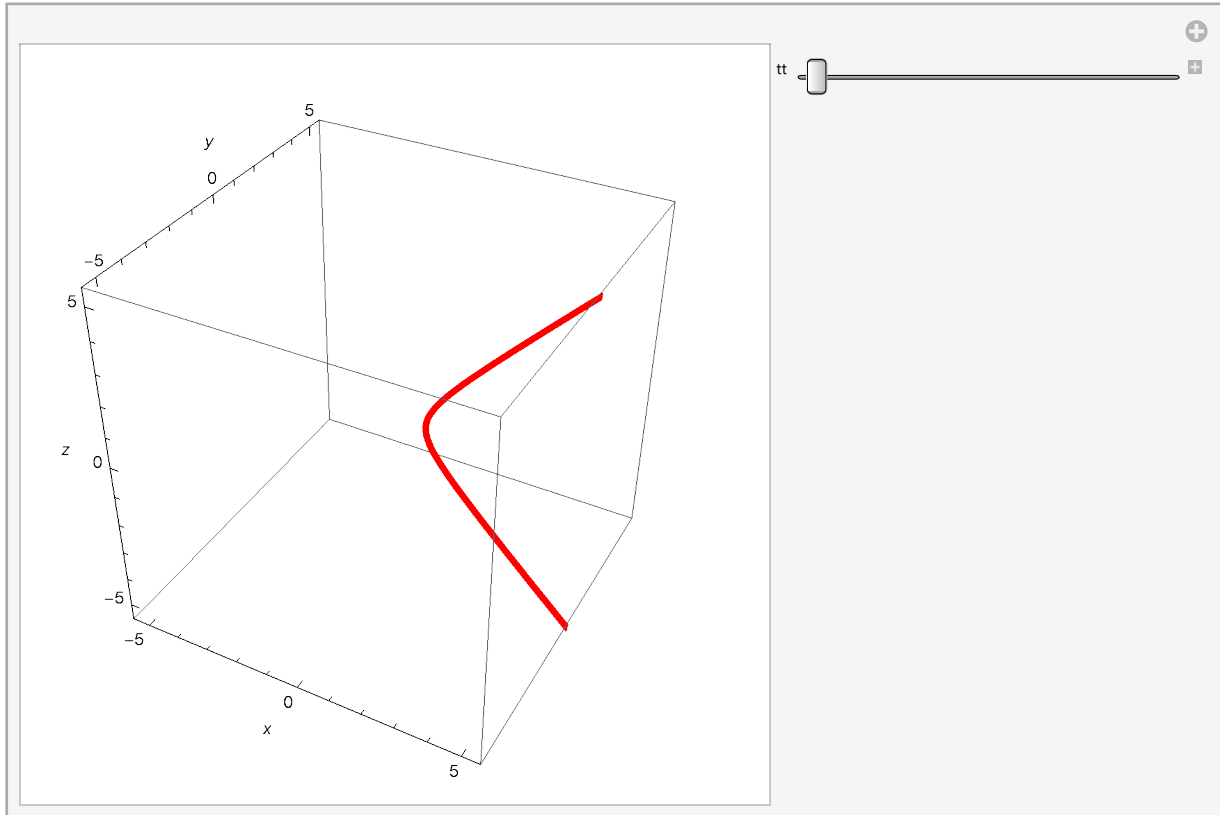


```

In[27]:= Manipulate[Show[ParametricPlot3D[{Cosh[s] Cos[θ], Cosh[s] Sin[θ], Sinh[s]},
  {s, -5, 5}, {θ, 0, tt}], PlotPoints → {50, 64}, Mesh → False],
  ParametricPlot3D[{Cosh[s] Cos[tt], Cosh[s] Sin[tt], Sinh[s]}, {s, -5, 5},
  PlotPoints → {50}], PlotStyle → {{Thickness[0.01], RGBColor[1, 0, 0]}},
  PlotRange → {{-5, 5}, {-5, 5}, {-5, 5}}, AxesLabel → {x, y, z}, {tt, 0.01, 2 Pi}]

```

Out[27]=



# Fun with Hyperboloid

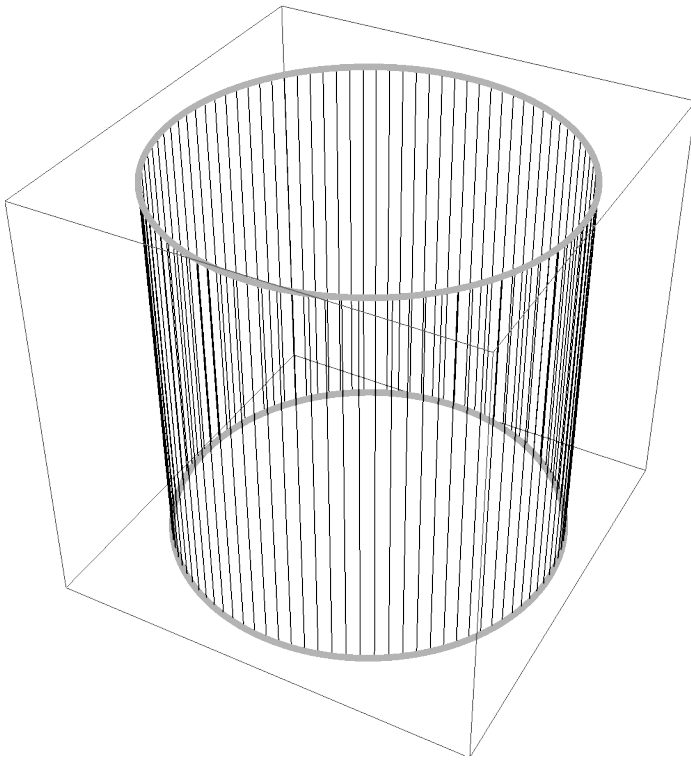
In[28]:= **Options[Graphics3D]**

```
Out[28]= {AlignmentPoint → Center, AspectRatio → Automatic, AutomaticImageSize → False,
  Axes → False, AxesEdge → Automatic, AxesLabel → None, AxesOrigin → Automatic,
  AxesStyle → {}, Background → None, BaselinePosition → Automatic, BaseStyle → {},
  Boxed → True, BoxRatios → Automatic, BoxStyle → {}, ClipPlanes → None,
  ClipPlanesStyle → Automatic, ColorOutput → Automatic, ContentSelectable → Automatic,
  ControllerLinking → False, ControllerMethod → Automatic, ControllerPath → Automatic,
  CoordinatesToolOptions → Automatic, DisplayFunction → $DisplayFunction,
  Epilog → {}, FaceGrids → None, FaceGridsStyle → {}, FormatType → TraditionalForm,
  ImageMargins → 0., ImagePadding → All, ImageSize → Automatic, ImageSizeRaw → Automatic,
  LabelStyle → {}, Lighting → Automatic, Method → Automatic, PlotLabel → None,
  PlotRange → All, PlotRangePadding → Automatic, PlotRegion → Automatic,
  PreserveImageOptions → Automatic, Prolog → {}, RotationAction → Fit,
  SphericalRegion → Automatic, Ticks → Automatic, TicksStyle → {},
  TouchscreenAutoZoom → False, ViewAngle → Automatic, ViewCenter → Automatic,
  ViewMatrix → Automatic, ViewPoint → {1.3, -2.4, 2.}, ViewProjection → Automatic,
  ViewRange → All, ViewVector → Automatic, ViewVertical → {0, 0, 1}}
```



```
In[29]= Graphics3D[{{Thickness[0.01], RGBColor[0.7, 0.7, 0.7],  
  Line[{Cos[#], Sin[#], 1} & /@ Range[0, 2 Pi,  $\frac{\text{Pi}}{64}$ ]}], {Thickness[0.01],  
  RGBColor[0.7, 0.7, 0.7], Line[{Cos[#], Sin[#], -1} & /@ Range[0, 2 Pi,  $\frac{\text{Pi}}{64}$ ]}],  
  {Line[{{Cos[#], Sin[#], 1}, {Cos[#], Sin[#], -1}}] & /@ Range[0, 2 Pi,  $\frac{\text{Pi}}{48}$ ]}],  
  PlotRange -> {{-1.1, 1.1}, {-1.1, 1.1}, {-1.1, 1.1}}]
```

Out[29]=

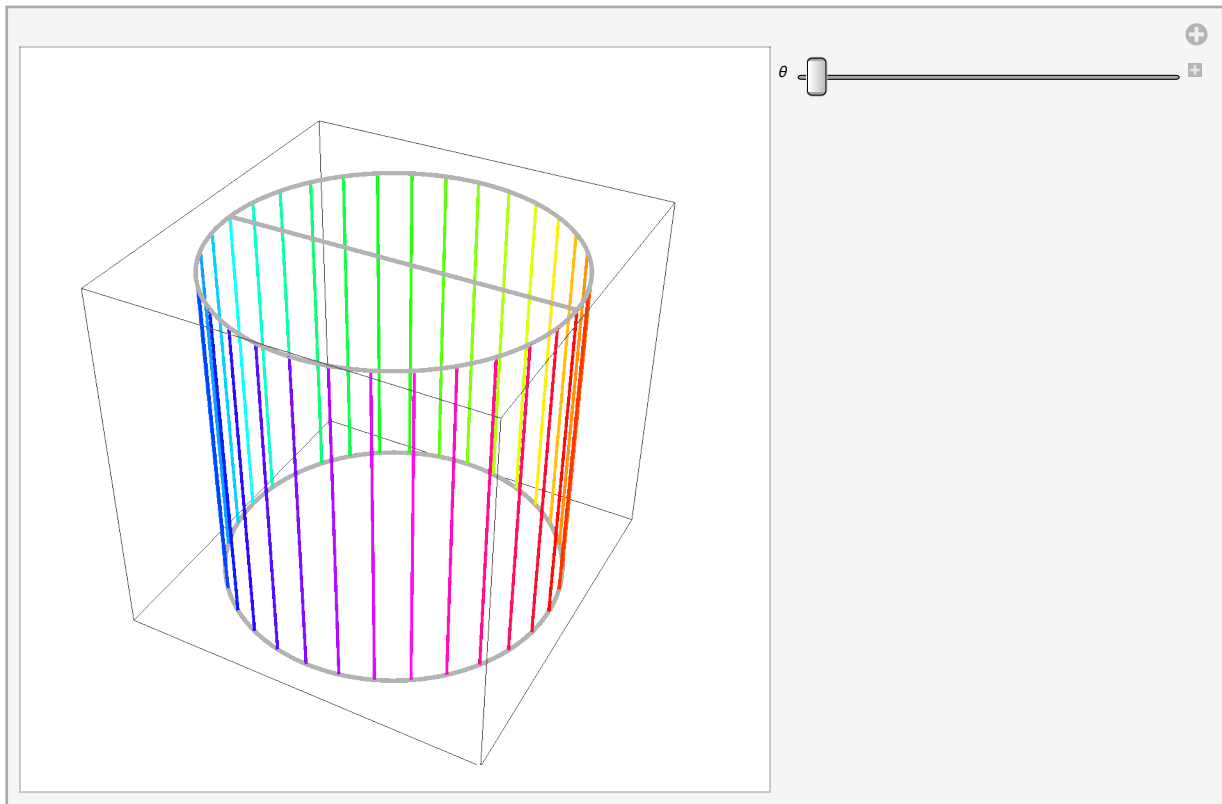


```

In[30]:= Manipulate[Graphics3D[{{Thickness[0.007],
  RGBColor[0.7, 0.7, 0.7], Line[{Cos[#], Sin[#], 1} & /@ Range[0, 2 Pi,  $\frac{\text{Pi}}$ ]}]},
  {Thickness[0.007], RGBColor[0.7, 0.7, 0.7],
  Line[{{0, 0, 1}, {Cos[0 + #], Sin[0 + #], 1}}] & /@ Range[0, 2 Pi, 2 Pi/2]},
  {Thickness[0.007], RGBColor[0.7, 0.7, 0.7],
  Line[{Cos[#], Sin[#], -1} & /@ Range[0, 2 Pi,  $\frac{\text{Pi}}$ ]}]}, {Thickness[0.005], Opacity[0.95],
  {Hue[# / (2 Pi)], Line[{{Cos[0 + #], Sin[0 + #], 1}, {Cos[#], Sin[#], -1}}] & /@
  Range[0, 2 Pi,  $\frac{\text{Pi}}$ ]}]},
  PlotRange -> {{-1.1, 1.1}, {-1.1, 1.1}, {-1.1, 1.1}}, {0, 0, 2 Pi}]

```

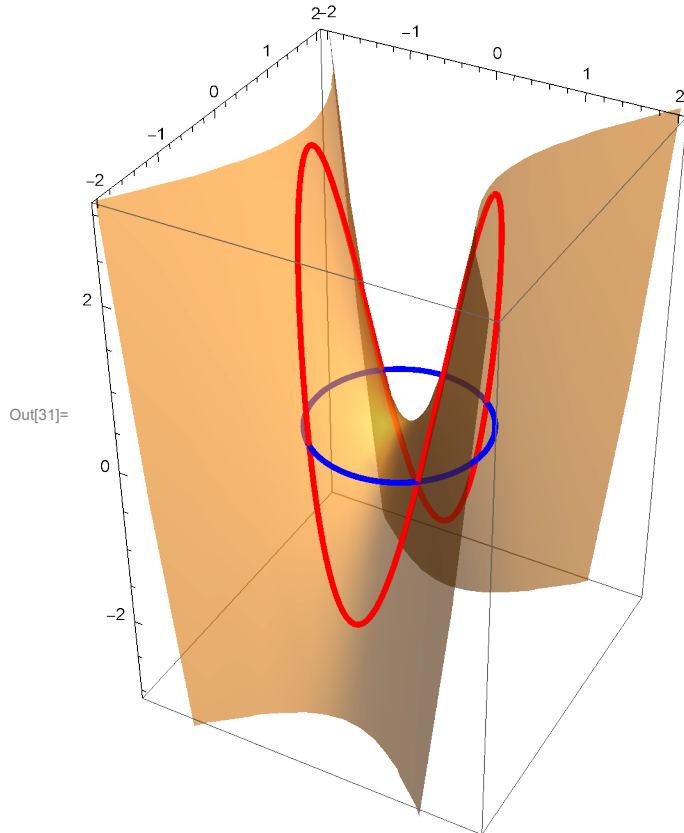
Out[30]=



```

In[31]:= Show[Plot3D[3 x^2 - 2 y^2, {x, -3, 3}, {y, -3, 3}, Mesh -> False, PlotStyle -> {Opacity[0.6]}],
Graphics3D[{Thickness[0.01], Blue, Line[Table[{Cos[t], Sin[t], 0}, {t, 0, 2 Pi, Pi/64}]]}],
Graphics3D[{Thickness[0.01], Red,
Line[Table[{Cos[t], Sin[t], 3 Cos[t]^2 - 2 Sin[t]^2}, {t, 0, 2 Pi, Pi/64}]]}],
PlotRange -> {{-2, 2}, {-2, 2}, {-3, 3}}, BoxRatios -> {1, 1, 3/2}]

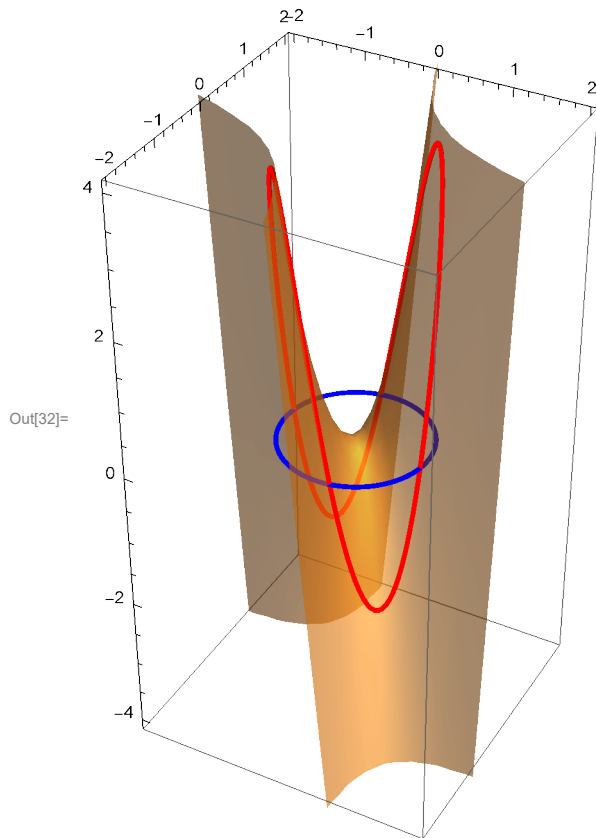
```



```

In[32]= Show[Plot3D[1 x^2 + 6 x y + 1 y^2, {x, -3, 3},
  {y, -3, 3}, Mesh -> False, PlotStyle -> {Opacity[0.6]}],
Graphics3D[{Thickness[0.01], Blue, Line[Table[{Cos[t], Sin[t], 0}, {t, 0, 2 Pi, Pi/64}]]}],
Graphics3D[{Thickness[0.01], Red,
  Line[Table[{Cos[t], Sin[t], 1 Cos[t]^2 + 6 Cos[t] Sin[t] + 1 Sin[t]^2}, {t, 0, 2 Pi, Pi/64}]]}],
PlotRange -> {{-2, 2}, {-2, 2}, {-4, 4}}, BoxRatios -> {1, 1, 4/2}]

```



```

In[33]:= Show[Plot3D[6 x^2 - 4 x y + 3 y^2, {x, -3, 3},
  {y, -3, 3}, Mesh -> False, PlotStyle -> {Opacity[0.6]}],
Graphics3D[{Thickness[0.01], Blue, Line[Table[{Cos[t], Sin[t], 0}, {t, 0, 2 Pi, Pi/64}]]}],
Graphics3D[{Thickness[0.01], Red,
  Line[Table[{Cos[t], Sin[t], 6 Cos[t]^2 - 4 Cos[t] Sin[t] + 3 Sin[t]^2}, {t, 0, 2 Pi, Pi/64}]]}],
PlotRange -> {{-2, 2}, {-2, 2}, {0, 8}}, BoxRatios -> {1, 1, 4/2}]

```

